STA 360/602L: MODULE 4.1

MULTIVARIATE NORMAL MODEL

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MULTIVARIATE DATA

- So far we have only considered basic models with scalar/univariate outcomes, Y_1, \ldots, Y_n .
- In practice however, outcomes of interest are actually often multivariate, e.g.,
 - Repeated measures of weight over time in a weight loss study
 - Measures of multiple disease markers
 - Tumor counts at different locations along the intestine
- Longitudinal data is just a special case of multivariate data.
- Interest then is often on how multiple outcomes are correlated, and on how that correlation may change across outcomes or time points.



MULTIVARIATE NORMAL DISTRIBUTION

- The most common model for multivariate outcomes is the multivariate normal distribution.
- Let $\mathbf{Y} = (Y_1, \dots, Y_p)^T$, where p represents the dimension of the multivariate outcome variable for a single unit of observation.
- For multiple observations, $oldsymbol{Y_i} = (Y_{i1}, \ldots, Y_{ip})^T$ for $i=1,\ldots,n.$
- $m{Y}$ follows a multivariate normal distribution, that is, $m{Y} \sim \mathcal{N}_p(m{\mu}, \Sigma)$, if

$$p(oldsymbol{y}|oldsymbol{\mu},\Sigma) = (2\pi)^{-rac{p}{2}}|\Sigma|^{-rac{1}{2}}\exp\left\{-rac{1}{2}(oldsymbol{y}-oldsymbol{\mu})^T\Sigma^{-1}(oldsymbol{y}-oldsymbol{\mu})
ight\},$$

where $|\Sigma|$ denotes the determinant of Σ .



MULTIVARIATE NORMAL DISTRIBUTION

If $oldsymbol{Y}\sim\mathcal{N}_p(oldsymbol{\mu},\Sigma)$, then

• $oldsymbol{\mu}$ is the p imes 1 mean vector, that is,

$$oldsymbol{\mu} = \mathbb{E}[oldsymbol{Y}] = \{\mathbb{E}[Y_1], \dots, \mathbb{E}[Y_p]\} = (\mu_1, \dots, \mu_p)^T.$$

- Σ is the $p \times p$ positive definite and symmetric covariance matrix, that is,
 - $\Sigma = \{\sigma_{jk}\}$, where σ_{jk} denotes the covariance between Y_j and Y_k .
- Y_1, \ldots, Y_p may be linearly dependent depending on the structure of Σ , which characterizes the association between them.
- For each $j=1,\ldots,p,$ $Y_j\sim\mathcal{N}(\mu_j,\sigma_{jj}).$



BIVARIATE NORMAL DISTRIBUTION

In the bivariate case, we have

$$oldsymbol{Y} = egin{pmatrix} Y_1 \ Y_2 \end{pmatrix} \sim \mathcal{N}_2 \left[\mu = egin{pmatrix} \mu_1 \ \mu_2 \end{pmatrix}, \Sigma = egin{pmatrix} \sigma_{11} = \sigma_1^2 & \sigma_{12} \ \sigma_{21} & \sigma_{22} = \sigma_2^2 \end{pmatrix}
ight],$$

and $\sigma_{12} = \sigma_{21} = \mathbb{C}\mathrm{ov}[Y_1,Y_2].$

- The correlation between Y_1 and Y_2 is defined as

$$ho_{1,2} = rac{\mathbb{C}\mathrm{ov}[Y_1,Y_2]}{\sqrt{\mathbb{V}\mathrm{ar}[Y_1]}\sqrt{\mathbb{V}\mathrm{ar}[Y_2]}} = rac{\sigma_{12}}{\sigma_1\sigma_2}.$$

- $-1 \le \rho_{1,2} \le 1$.
- Correlation coefficient is free of the measurement units.



BACK TO THE MULTIVARIATE NORMAL

- There are many special properties of the multivariate normal as we will see as we continue to work with the distribution.
- First, dependence between any Y_j and Y_k does not depend on the other p-2 variables.
- Second, while generally, independence implies zero covariance, for the normal family, the converse is also true. That is, zero covariance also implies independence.
- Thus, the covariance Σ carries a lot of information about marginal relationships, especially marginal independence.
- If $m{\epsilon}=(\epsilon_1,\ldots,\epsilon_p)\sim\mathcal{N}_p(m{0},m{I}_p)$, that is, $\epsilon_1,\ldots,\epsilon_p\stackrel{iid}{\sim}\mathcal{N}(0,1)$, then

$$oldsymbol{Y} = oldsymbol{\mu} + Aoldsymbol{\epsilon} \Rightarrow oldsymbol{Y} \sim \mathcal{N}_p(oldsymbol{\mu}, \Sigma)$$

holds for any matrix square root A of Σ , that is, $AA^T = \Sigma$ (see Cholesky decomposition).



CONDITIONAL DISTRIBUTIONS

- Partition
$$oldsymbol{Y} = (Y_1, \dots, Y_p)^T$$
 as

$$oldsymbol{Y} = egin{pmatrix} oldsymbol{Y}_1 \ oldsymbol{Y}_2 \end{pmatrix} \sim \mathcal{N}_p \left[egin{pmatrix} oldsymbol{\mu}_1 \ oldsymbol{\mu}_2 \end{pmatrix}, egin{pmatrix} \Sigma_{11} & \Sigma_{12} \ \Sigma_{21} & \Sigma_{22} \end{pmatrix}
ight],$$

where

- $oldsymbol{Y}_1$ and $oldsymbol{\mu}_1$ are q imes 1,
- $oldsymbol{Y}_2$ and $oldsymbol{\mu}_2$ are (p-q) imes 1,
- Σ_{11} is q imes q, and
- Σ_{22} is (p-q) imes (p-q), with $\Sigma_{22}>0.$
- Then,

 $oldsymbol{Y}_1|oldsymbol{Y}_2=oldsymbol{y}_2\sim\mathcal{N}_q\left(oldsymbol{\mu}_1+\Sigma_{12}\Sigma_{22}^{-1}(oldsymbol{y}_2-oldsymbol{\mu}_2),\Sigma_{11}-\Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}
ight).$

Marginal distributions are once again normal, that is,

$$oldsymbol{Y}_1 \sim \mathcal{N}_q\left(oldsymbol{\mu}_1, \Sigma_{11}
ight); \;\; oldsymbol{Y}_2 \sim \mathcal{N}_{p-q}\left(oldsymbol{\mu}_2, \Sigma_{22}
ight).$$



CONDITIONAL DISTRIBUTIONS

In the bivariate normal case with

$$oldsymbol{Y} = egin{pmatrix} Y_1 \ Y_2 \end{pmatrix} \sim \mathcal{N}_2 \left[\mu = egin{pmatrix} \mu_1 \ \mu_2 \end{pmatrix}, \Sigma = egin{pmatrix} \sigma_{11} = \sigma_1^2 & \sigma_{12} \ \sigma_{21} & \sigma_{22} = \sigma_2^2 \end{pmatrix}
ight],$$

we have

$$Y_1|Y_2=y_2\sim \mathcal{N}\left(\mu_1+rac{\sigma_{12}}{\sigma_2^2}(y_2-\mu_2),\sigma_1^2-rac{\sigma_{12}^2}{\sigma_2^2}
ight).$$

which can also be written as

$$Y_1|Y_2=y_2\sim \mathcal{N}\left(\mu_1+rac{\sigma_1}{\sigma_2}
ho(y_2-\mu_2),(1-
ho^2)\sigma_1^2
ight).$$



• Suppose
$$oldsymbol{Y}_i = (Y_{i1},\ldots,Y_{ip})^T \sim \mathcal{N}_p(oldsymbol{ heta},\Sigma), \, i=1,\ldots,n.$$

• Write $oldsymbol{Y} = (oldsymbol{y}_1, \dots, oldsymbol{y}_n)^T.$ The resulting likelihood can then be written as

$$p(oldsymbol{Y}|oldsymbol{ heta},\Sigma) = \prod_{i=1}^n (2\pi)^{-rac{p}{2}} |\Sigma|^{-rac{1}{2}} \exp\left\{-rac{1}{2}(oldsymbol{y}_i-oldsymbol{ heta})^T \Sigma^{-1}(oldsymbol{y}_i-oldsymbol{ heta})
ight\} \ \propto |\Sigma|^{-rac{n}{2}} \exp\left\{-rac{1}{2}\sum_{i=1}^n (oldsymbol{y}_i-oldsymbol{ heta})^T \Sigma^{-1}(oldsymbol{y}_i-oldsymbol{ heta})
ight\}.$$

• It will be super useful to be able to write the likelihood in two different formulations depending on whether we care about the posterior of θ or Σ .



- For inference on $\pmb{\theta},$ it is convenient to write $p(\pmb{Y}|\pmb{\theta}, \Sigma)$ as

$$\begin{split} p(\mathbf{Y}|\boldsymbol{\theta},\boldsymbol{\Sigma}) \propto \underbrace{|\boldsymbol{\Sigma}|^{-\frac{n}{2}}}_{\text{does not involve }\boldsymbol{\theta}} & \exp\left\{-\frac{1}{2}\sum_{i=1}^{n}(\boldsymbol{y}_{i}-\boldsymbol{\theta})^{T}\boldsymbol{\Sigma}^{-1}(\boldsymbol{y}_{i}-\boldsymbol{\theta})\right\}\\ & \propto \exp\left\{-\frac{1}{2}\sum_{i=1}^{n}(\boldsymbol{y}_{i}^{T}-\boldsymbol{\theta}^{T})\boldsymbol{\Sigma}^{-1}(\boldsymbol{y}_{i}-\boldsymbol{\theta})\right\}\\ & = \exp\left\{-\frac{1}{2}\sum_{i=1}^{n}\left[\underbrace{\boldsymbol{y}_{i}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{y}_{i}}_{\text{does not involve }\boldsymbol{\theta}} - \underbrace{\boldsymbol{y}_{i}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{\theta} - \boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{y}_{i}}_{\text{same term}} + \boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{\theta}\right]\right\}\\ & \propto \exp\left\{-\frac{1}{2}\sum_{i=1}^{n}\left[\boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{\theta} - 2\boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{y}_{i}\right]\right\}\\ & = \exp\left\{-\frac{1}{2}\sum_{i=1}^{n}\boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{\theta} - \frac{1}{2}\sum_{i=1}^{n}(-2)\boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{y}_{i}\right\}\\ & = \exp\left\{-\frac{1}{2}n\boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\boldsymbol{\theta} + \boldsymbol{\theta}^{T}\boldsymbol{\Sigma}^{-1}\sum_{i=1}^{n}\boldsymbol{y}_{i}\right\}\\ & = \exp\left\{-\frac{1}{2}n\boldsymbol{\theta}^{T}(n\boldsymbol{\Sigma}^{-1})\boldsymbol{\theta} + \boldsymbol{\theta}^{T}(n\boldsymbol{\Sigma}^{-1})\boldsymbol{y}_{i}\right\}, \end{split}$$

where
$$ar{oldsymbol{y}}=({ar{y}}_1,\ldots,{ar{y}}_p)^T.$$



- For inference on Σ , we need to rewrite the likelihood a bit.
- First a few results from matrix algebra:
 - 1. $\operatorname{tr}(\boldsymbol{A}) = \sum_{j=1}^{p} a_{jj}$, where a_{jj} is the jth diagonal element of a square $p \times p$ matrix \boldsymbol{A} , where $\operatorname{tr}(\cdot)$ is the trace function (sum of diagonal elements).
 - 2. Cyclic property:

$$\operatorname{tr}(\boldsymbol{ABC}) = \operatorname{tr}(\boldsymbol{BCA}) = \operatorname{tr}(\boldsymbol{CAB}),$$

given that the product ABC is a square matrix.

3. If $oldsymbol{A}$ is a p imes p matrix, then for a p imes 1 vector $oldsymbol{x}$,

$$\boldsymbol{x}^T \boldsymbol{A} \boldsymbol{x} = \operatorname{tr}(\boldsymbol{x}^T \boldsymbol{A} \boldsymbol{x})$$

holds by (1), since $oldsymbol{x}^T oldsymbol{A} oldsymbol{x}$ is a scalar.

4. $\operatorname{tr}(\boldsymbol{A} + \boldsymbol{B}) = \operatorname{tr}(\boldsymbol{A}) + \operatorname{tr}(\boldsymbol{B}).$



- It is convenient to rewrite $p(oldsymbol{Y}|oldsymbol{ heta},\Sigma)$ as

$$p(\boldsymbol{Y}|\boldsymbol{\theta}, \boldsymbol{\Sigma}) \propto |\boldsymbol{\Sigma}|^{-\frac{n}{2}} \exp\left\{-\frac{1}{2} \sum_{i=1}^{n} (\boldsymbol{y}_{i} - \boldsymbol{\theta})^{T} \boldsymbol{\Sigma}^{-1} (\boldsymbol{y}_{i} - \boldsymbol{\theta})\right\}$$
no algebra/change yet
$$= |\boldsymbol{\Sigma}|^{-\frac{n}{2}} \exp\left\{-\frac{1}{2} \sum_{i=1}^{n} \underbrace{\operatorname{tr}\left[(\boldsymbol{y}_{i} - \boldsymbol{\theta})^{T} \boldsymbol{\Sigma}^{-1} (\boldsymbol{y}_{i} - \boldsymbol{\theta})\right]\right\}}_{\text{by result 3}}\right\}$$

$$= |\boldsymbol{\Sigma}|^{-\frac{n}{2}} \exp\left\{-\frac{1}{2} \sum_{i=1}^{n} \underbrace{\operatorname{tr}\left[(\boldsymbol{y}_{i} - \boldsymbol{\theta})(\boldsymbol{y}_{i} - \boldsymbol{\theta})^{T} \boldsymbol{\Sigma}^{-1}\right]\right\}}_{\text{by cyclic property}}\right\}$$

$$= |\boldsymbol{\Sigma}|^{-\frac{n}{2}} \exp\left\{-\frac{1}{2} \operatorname{tr}\left[\sum_{i=1}^{n} (\boldsymbol{y}_{i} - \boldsymbol{\theta})(\boldsymbol{y}_{i} - \boldsymbol{\theta})^{T} \boldsymbol{\Sigma}^{-1}\right]\right\}$$

$$= |\boldsymbol{\Sigma}|^{-\frac{n}{2}} \exp\left\{-\frac{1}{2} \operatorname{tr}\left[\boldsymbol{S}_{\boldsymbol{\theta}} \boldsymbol{\Sigma}^{-1}\right]\right\},$$



where $m{S}_{ heta} = \sum_{i=1}^n (m{y}_i - m{ heta}) (m{y}_i - m{ heta})^T$ is the residual sum of squares matrix.

WHAT'S NEXT?

Move on to the readings for the next module!

